

# φ 30 Body Standard Shaft Type

## Diameter φ 30mm shaft type INCREMENTAL Rotary encoder

### ■ Features

- φ 30mm shaft type rotary encoder
- Easy installation at narrow space
- Small inertia moment
- Wide range of power source : 5VDC, 12-24VDC ±5%
- Various output types



**⚠ Please read "Caution for your safety" in operation manual before using.**



### ■ Ordering information

<b>E30S</b>	<b>4</b>	<b>—</b>	<b>1024</b>	<b>—</b>	<b>3</b>	<b>—</b>	<b>2</b>	<b>—</b>	<b>24</b>	<b>—</b>	
Series	Shaft diameter	Pulse/1Revolution	Output phase	Output	Power supply	Cable					
Diameter φ 30mm, shaft type	φ 4mm	See resolution	2:A, B 3:A, B, Z 4:A, $\bar{A}$ , B, $\bar{B}$ 6:A, $\bar{A}$ , B, $\bar{B}$ , Z, $\bar{Z}$	1:Totem pole output 2:NPN open collector output 3:Voltage output L:Line driver output(※)	5 :5VDC ±5% 24:12-24VDC ±5%	No mark:Normal type (※) 2C:Cable outgoing connector type					

※Standard:E30S4-PULSE-3-2-24(12-24VDC) ※Standard:A, B, Z ※The power of Line driver is only for 5VDC ※Cable length:200mm

### ■ Specifications

Item	Diameter φ 30mm shaft type Incremental Rotary encoder		
Resolution(P/R)	100, 200, 360, 500, 1000, 1024, 3000 (Not indicated type is available to customize)		
Electrical specification	Phase difference of output	Output between A and B phase : $\frac{T}{4} \pm \frac{T}{8}$ (T=1cycle of A phase)	
	Control output	Totem pole output	• Low $\Rightarrow$ Load current : Max. 30mA, Residual voltage : Max. 0.4VDC • High $\Rightarrow$ Load current : Max. 10mA, Output voltage : Min. (Power voltage-1.5)VDC
		NPN open collector output	Load current : Max. 30mA, Residual voltage : Max. 0.4VDC
		Voltage output	Load current : Max. 10mA, Residual voltage : Max. 0.4VDC
		Line driver output	Low $\Rightarrow$ Load current : Max. 20mA, Residual : Max. 0.5V High $\Rightarrow$ Load current : Max. -20mA, Output voltage : Min. 2.5V
	Response time (Rise/Fall)	Totem pole output	Max. 1μs
		NPN open collector output	Max. 1μs
		Voltage output	Max. 1μs (5VDC:Output resistance 820Ω), Max. 2μs (12-24VDC:Output resistance 4.7kΩ)
		Line driver output	Max. 0.5μs
	Max. Response frequency	180kHz	
Current consumption	Max. 60mA(disconnection of the load), Line driver output:Max. 50mA(disconnection of the load)		
Insulation resistance	Min. 100MΩ (at 500VDC)		
Dielectric strength	750VAC 50/60Hz for 1 minute(Between all terminals and case)		
Connection	Cable outgoing type, 200mm cable outgoing connector type		
Mechanical specification	Starting torque	Max. 20gf · cm(0.002N · m)	
	Moment of inertia	Max. 20g · cm <sup>2</sup> (2×10 <sup>-6</sup> kg · m <sup>2</sup> )	
	Shaft loading	Radial : Max. 2kgf, Thrust : Max. 1kgf	
	Deviation of shaft position	Radial : Max. 0.1mm, Thrust : Max. 0.2mm	
	Max. allowable revolution	<b>(★Note1)</b> 5000rpm	
Vibration	1.5mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 2 hours		
Shock	Max. 50G		
Ambient temperature	-10 ~ 70℃ (at non-freezing status), Storage:-25 ~ 85℃		
Ambient humidity	35~85%RH, Storage: 35~90%RH		
Protection	IP50(IEC specification)		
Cable	<b>(★Note2)</b> 5P, (Line driver:8P) φ 5mm, Length:2m, Shield cable(Basic)		
Accessory	φ 4mm coupling		
Weight	Approx. 80g		
Approval	<b>CE</b> (Except Line driver output)		

※(★Note1)Max. allowable revolution ≥ Max. response revolution **[Max. response revolution(rpm) =  $\frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec}$ ]**  
Please select the resolution to make lower max. revolution than max. allowable revolution.

※(★Note2)The cable length is changeable. (Option)

(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/Speed/Pulse meter

(G) Display unit

(H) Sensor controller

(I) Proximity sensor

(J) Photo electric sensor

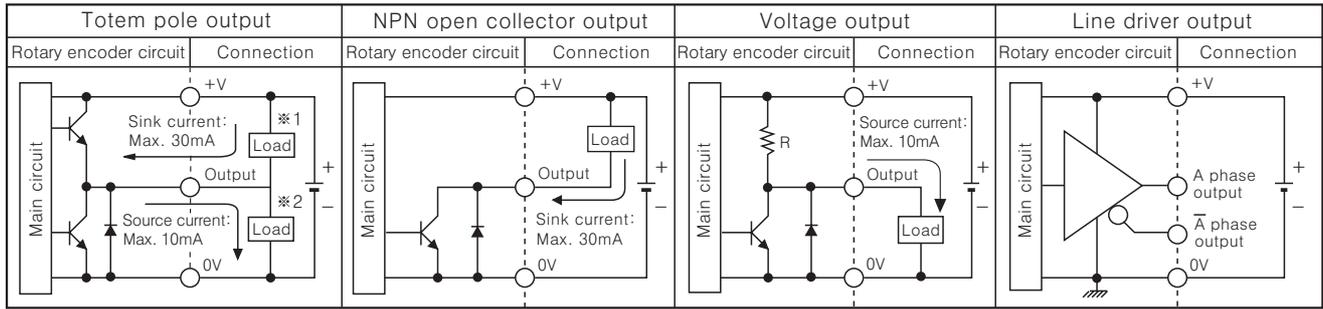
(K) Pressure sensor

(L) Rotary encoder

(M) 5-Phase stepping motor & Driver & Controller

# E30S4 Series

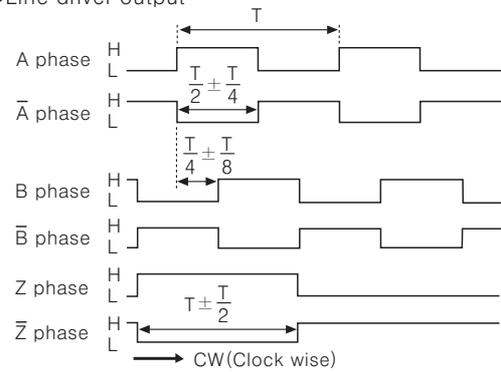
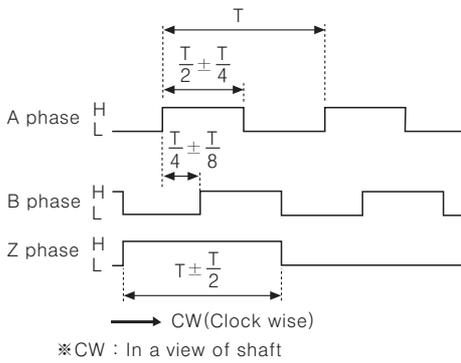
## Control output diagram



⊞ Totem pole output type can be used for NPN open collector output type(\*1) or Voltage output type(\*2).  
 ⊞ All output circuits are the same A, B, Z phase(Line driver output is A,  $\bar{A}$ , B,  $\bar{B}$ , Z,  $\bar{Z}$ )

## Output waveform

- Totem pole output / NPN open collector output / Voltage output
- Line driver output



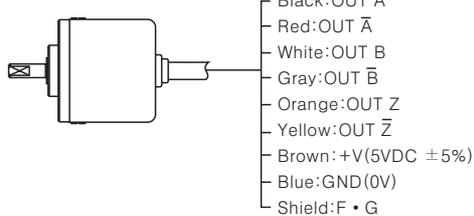
## Connections

### Normal type

- Totem pole output / NPN open collector output / Voltage output

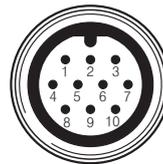


- Line driver output



⊞ The body of encoder is connected to a shield.  
 ⊞ Unused wires must be insulated.

### Cable outgoing connector type

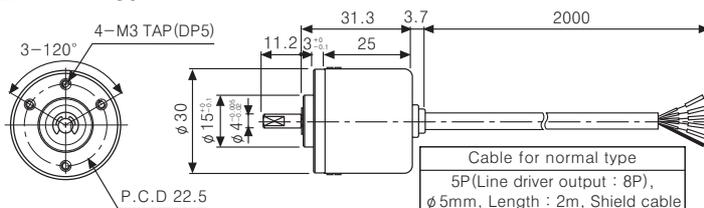


Pin No.	Cable color	Totem pole output NPN open collector output Voltage output	Line driver output
①	Black	OUT A	OUT A
②	Red	N.C	OUT $\bar{A}$
③	Brown	+V	+V
④	Blue	GND	GND
⑤	White	OUT B	OUT B
⑥	Gray	N.C	OUT $\bar{B}$
⑦	Orange	OUT Z	OUT Z
⑧	Yellow	N.C	OUT $\bar{Z}$
⑨	Shield	F.G	F.G
⑩	Purple	N.C	N.C

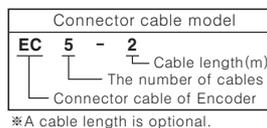
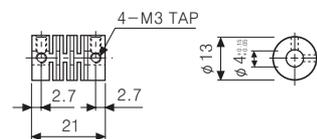
⊞ N.C(Not Connected)  
 ⊞ F.G(Field Ground)

## Dimensions

### Normal type

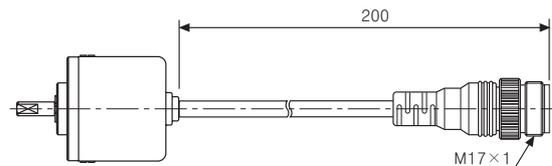


- Coupling

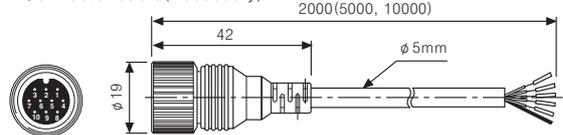


### Cable outgoing connector type

Unit:mm



- Connector cable(Accessory)



⊞ Connector cable model ⊞ Line driver output : EC8-2(Standard), EC8-5, EC8-10  
 ⊞ Etc. : EC5-2(Standard), EC5-5, EC5-10